# **MFA Series**

# Miniature Linear Stages











USER'S MANUAL

For Motion, Think Newport

# Warranty

Newport Corporation warrants this product to be free from defects in material and workmanship for a period of 1 year from the date of shipment. If found to be defective during the warranty period, the product will either be repaired or replaced at Newport's discretion.

To exercise this warranty, write or call your local Newport representative, or contact Newport headquarters in Irvine, California. You will be given prompt assistance and return instructions. Send the instrument, transportation prepaid, to the indicated service facility. Repairs will be made and the instrument returned, transportation prepaid. Repaired products are warranted for the balance of the original warranty period, or at least 90 days.

### **Limitation of Warranty**

This warranty does not apply to defects resulting from modification or misuse of any product or part.

### **CAUTION**

Warranty does not apply to damages resulting from:

- Incorrect usage:
  - Load on the stage greater than maximum specified load.
  - Carriage speed higher than specified speed.
  - Improper grounding.
    - ¬ Connectors must be properly secured.
    - ¬ When the load on the stage represents an electrical risk, it must be connected to ground.
  - Excessive or improper cantilever loads.
- Modification of the stage or any part thereof.

This warranty is in lieu of all other warranties, expressed or implied, including any implied warranty of merchantability or fitness for a particular use. Newport Corporation shall not be liable for any indirect, special, or consequential damages.

No part of this manual may be reproduced or copied without the prior written approval of Newport Corporation.

This manual has been provided for information only and product specifications are subject to change without notice. Any changes will be reflected in future printings.



### **CAUTION**

Please return equipment in the original (or equivalent) packing.

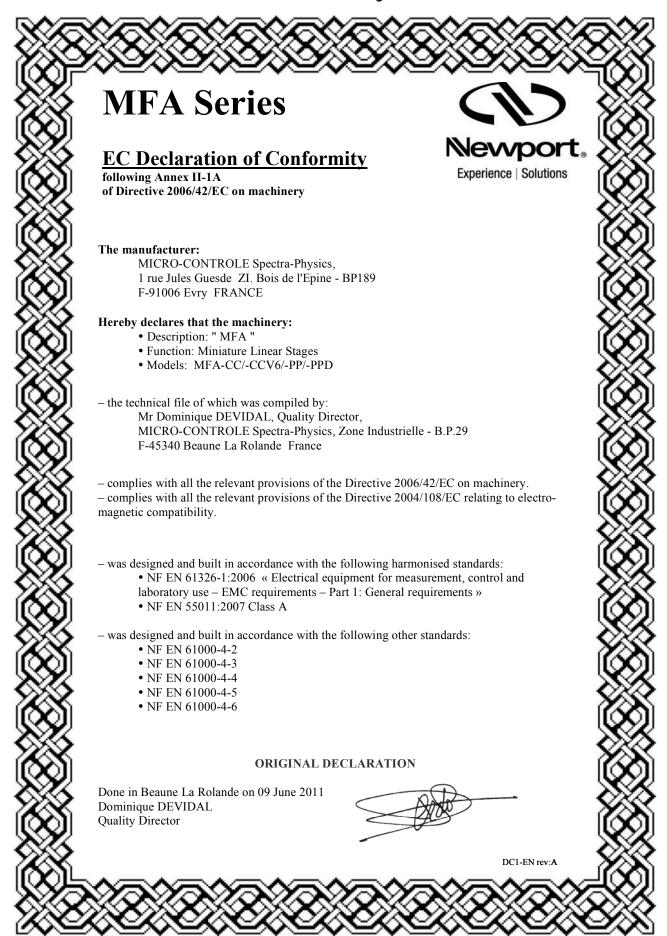
You will be responsible for damage incurred from inadequate packaging if the original packaging is not used.

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# **EC Declaration of Conformity**



# **Definitions and Symbols**

The following terms and symbols are used in this documentation and also appear on the product where safety-related issues occur.

### **General Warning or Caution**



The exclamation symbol may appear in warning and caution tables in this document. This symbol designates an area where personal injury or damage to the equipment is possible.

### **European Union CE Mark**



The presence of the CE Mark on Newport Corporation equipment means that it has been designed, tested and certified as complying with all applicable European Union (CE) regulations and recommendations.



### **ATTENTION**

This stage is a Class A device. In a residential environment, this device can cause radioelectric interferences. In this case, suitable measurements must be taken by the user of this device.

### **Warnings and Cautions**

The following are definitions of the Warnings, Cautions and Notes that may be used in this manual to call attention to important information regarding personal safety, safety and preservation of the equipment, or important tips.



### **WARNING**

Situation has the potential to cause bodily harm or death.



### **CAUTION**

Situation has the potential to cause damage to property or equipment.

#### **NOTE**

Additional information the user or operator should consider.

## Warnings



#### WARNING

The motion of objects of all types carries potential risks for operators. Ensure the protection of operators by prohibiting access to the dangerous area and by informing the personnel of the potential risks involved.

#### WARNING

Do not use this stage when its motor is emitting smoke or is unusually hot to the touch or is emitting any unusual odor or noise or is in any other abnormal state.

Stop using the stage immediately, switch off the motor power and then disconnect the electronics power supply.

After checking that smoke is no longer being emitted contact your Newport service facility and request repairs. Never attempt to repair the stage yourself as this can be dangerous.

#### WARNING

Make sure that this stage is not exposed to moisture and that liquid does not get into the stage.

Nevertheless, if any liquid has entered the stage, switch off the motor power and then disconnect the electronics from power supply.

Contact your Newport service facility and request repairs.



#### WARNING

Do not insert or drop objects into this stage, this may cause an electric shock, or lock the drive.

Do not use this stage if any foreign objects have entered the stage. Switch off the motor power and then disconnect the electronics power supply.

Contact your Newport service facility for repairs.

### WARNING

Do not place this stage in unstable locations such as on a wobbly table or sloping surface, where it may fall or tip over and cause injury.

If this stage has been dropped or the case has been damaged, switch off the motor power and then disconnect the electronics power supply.

Contact your Newport service facility and request repairs.

### WARNING

Do not attempt to modify this stage; this may cause an electric shock or downgrade its performance.

#### **WARNING**

Do not exceed the usable depth indicated on the mounting holes (see section "Dimensions"). Longer screws can damage the mechanics or cause a short-circuit.

### **Cautions**

#### **CAUTION**

Do not place this stage in a hostile environment such as X-Rays, hard UV,... or in any vacuum environment.

#### **CAUTION**

Do not place this stage in a location affected by dust, oil fumes, steam or high humidity. This may cause an electric shock.

#### **CAUTION**

Do not leave this stage in places subject to extremely high temperatures or low temperatures. This may cause an electric shock.

- Operating temperature: +10 to +35 °C.
- Storage temperature: -10 to +40 °C (in its original packaging).

### **CAUTION**



Do not move this stage if its motor power is on.

Make sure that the cable to the electronics is disconnected before moving the stage. Failure to do so may damage the cable and cause an electrical shock.

#### **CAUTION**

Be careful that the stage is not bumped when it is being carried. This may cause it to malfunction.

#### **CAUTION**

When handling this stage, always unplug the equipment from the power source for safety.

### **CAUTION**

When the carriage is in its end-of-run position, it is strongly recommended not to go beyond this point by using the manual knob as this may damage the stage mechanism.

### **CAUTION**

Contact your Newport service facility to request cleaning and specification control every year.

# Miniature Linear Stages MFA Series

1.0

### Introduction

This manual provides operating instructions for the stage that you have purchased in the MFA Series:

• MFA-CC

• MFA-CCV6 (1)

• MFA-PP

• MFA-PPD

#### 1) REMARK

Vacuum compatible stages to  $10^6$  hPa. In this case, max. speed and load capacity have to be divided by two.



MFA-CC miniature linear stage.

### RECOMMENDATION

We recommend you read carefully the chapter "Connection to electronics" before using the MFA stage.



MFA stages in an XYZ configuration.

### **Description**

Designed for space-limited applications and compact multi-axis assemblies, MFA Series linear stages supply very high resolution, single-axis translation in a low-cost, motorized package. Typical applications for this stage are fiber optic alignment, laser diode research, bio-medical applications and inspection systems.

MFA linear stages are available in two versions: The MFA-CC with a DC-motor, features an integrated gear-box and a motormounted high resolution 2,048 cts/rev rotary encoder. The highresolution position feedback and low-friction mechanical design ensures ultra-smooth motion with 100 nm sensitivity. The DC motor supplies an optimized output torque that permits the use of a lower ratio step-down gear allowing for faster motion with higher reliability and lower backlash. Hence, the MFA-CC is the recommended choice for applications that require small incremental motion with high dynamic speed range and good repeatability. The MFA-PP and MFA-PPD stepper motor versions are more economical solutions for less demanding applications.

Travel limit switches prevent bearing damage from accidental over-travel.

MFA stages feature an all-steel construction that provides a higher stiffness-to-weight ratio and lower thermal expansion compared to aluminum designs. The result is superior performance in a smaller footprint. The smooth motion of the MFA linear stages is further accentuated by Newport's proprietary double-row linear ball bearing design with bearing ways that are directly machined into the structural frame of the stage. Compared to other solutions that use commercial bearings, MFA linear stages have a higher load capacity and stiffness with low pitch and yaw errors.

Another benefit of Newport's integrated bearing ways is the availability of 4 widely spaced mounting holes for base mounting and XY-assemblies. This provides better stress distribution and allows for more rigid multi-axis combinations than other designs that provide only line contact with 2 mounting holes.

#### 2.1 Design Details

Base Material	Stainless steel
Bearings	Double row linear ball bearings
Drive Mechanism	Backlash compensated leadscrew
Feedback	MFA-CC: Motor mounted rotary encoder; 2,048 cts/rev
	MFA-PP: None
Limit Switches	Optical switches
Origin	Uses motor side limit for homing, typically <5 mm repeatability
Cable (m)	1.5 (included)
Vacuum Compatibility	Vacuum compatible versions are available up to 10-6 hPa using DC motor (MFA-CCV6).
	Maximum load, speed and acceleration are halved.



### **NOTE**

This product complies with the RoHS directive (Restriction of Hazardous Substances)

### **Characteristics**

#### 3.1 Definitions

Specifications of our products are established in reference to ISO 230 standard part II "Determination of the position, precision and repeatability of the machine tools with CNC".

This standard gives the definition of position uncertainty which depends on the 3 following quantities:

### (Absolute) Accuracy

Difference between ideal position and real position.

### **On-Axis Accuracy**

Difference between ideal position and real position after the compensation of linear errors.

Linear errors include: cosine errors, inaccuracy of screw or linear scale pitch, angular deviation at the measuring point (Abbe error) and thermal expansion effects. All Newport motion electronics can compensate for linear errors.

The relation between absolute accuracy and on-axis accuracy is as follows:

Absolute Accuracy = On-Axis Accuracy + Correction Factor x Travel

### Repeatability

Ability of a system to achieve a commanded position over many attempts.

#### **Reversal Value (Hysteresis)**

Difference between actual position values obtained for a given target position when approached from opposite directions.

#### **Minimum Incremental Motion (Sensitivity)**

The smallest increment of motion a device is capable of delivering consistently and reliably.

#### Resolution

The smallest increment that a motion device can be commanded to move and/or detect.

#### Resolution

The smallest increment that a motion device can be commanded to move and/or detect.

### Yaw, Pitch

Rotation of carriage around the Z axis (Yaw) or Y axis (Pitch), when it moves.

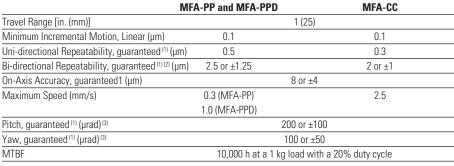
The testing of on-axis accuracy, repeatability, and reversal error are made systematically with test equipment in an air-conditioned room (20  $^{\circ}$ C  $^{\pm1}$   $^{\circ}$ C).

A linear cycle with 21 data points on the travel and 4 cycles in each direction gives a total of 164 points.

### **Guaranteed Specifications**

Guaranteed maximum performance values are verified per the Newport's A167 metrology test procedure. For more information, please consult the metrology tutorial section in the Newport catalog or on the Newport web site at **www.newport.com** 

### 3.2 Mechanical Specifications





Shown are peak to peak, guaranteed specifications or  $\pm$  half the value as sometimes shown. For the definition of typical specifications which are about 2X better than the guaranteed values.

<sup>&</sup>lt;sup>3)</sup> To obtain arcsec units, divide mrad value by 4.8.



#### **CAUTION**

To reach specifications stated, stages must be fixed on a plane surface with a flatness of 5  $\mu m. \,$ 

### 3.3 Load Specification Definitions

### **Normal Load Capacity (Cz)**

Maximum load a stage can move while maintaining specifications.

This value is given with speed and acceleration specified for each stage, and with a load perpendicular to bearings.

### Axial Load Capacity (±Cx)

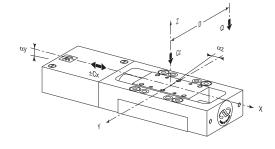
Maximum load along the direction of the drive train.

### Off-Centered Load (Q)

Maximum cantilever-load a stage can move:  $Q \le Cz / (1 + D/20)$ 

D: Cantilever distance.

#### 3.4 Load Characteristics and Stiffness



Cz, Normal centered load capacity	50 N
-Cx, +Cx, Axial load capacity	10 N
kαx, Compliance in roll	60 μrad/Nm
kαy, Compliance in pitch	10 μrad/Nm
Q, Off-center load	$0 \le Cz/(1 + D/20)$
D, Cantilever distance in mm	

<sup>2)</sup> After backlash compensation..

### **REMARK**

For MFA-CCV6 vacuum compatible stages to 10<sup>6</sup> hPa, max. speed and load capacity have to be divided by two.

### 3.5 Stage Weights

The weight indicated is the average value for stages with their cable installed.

	Weight [lb (kg)]
MFA	1.3 (0.6)

The weight variation between drive units is not very significant.

4.0

**Drive** 

#### 4.1 DC-Motor Drive Version

One DC-motor-driven configuration is available: MFA-CC.

### **DC-Motor Performance Specifications**

	Resolution	Speed	Motor
	(µm)	(mm/s)	Motor
MFA-CC	0.0174	2.5	UE1724SR
,			

### **REMARK**

For MFA-CCV6 vacuum compatible stages to 10<sup>6</sup> hPa, max. speed and load capacity have to be divided by two.

### 4.2 Stepper Drive Version

Stepper-motor-driven stages are offered in one half-step drive version: MFA-PP & MFA-PPD.

### **Micro-Step Drive**

This is the drive for stepper or pulse-driven motors, transmitted by the electronic unit, which entails a theoretical movement of the motor by one fraction of a full-step. For these translation stages, the micro-step is equivalent to 1/64 of the full-step.

#### **Stepper Motor Performance Specifications**

	Resolution (1)	Speed	Motor	
	(µm)	(mm/s)	Motor	
MFA-PP	- 0.00757	0.3	- UE16PP	
MFA-PPD	— 0.00 <i>1</i> 31	1	- UEIOFF	

<sup>1)</sup> Micro-step driving.

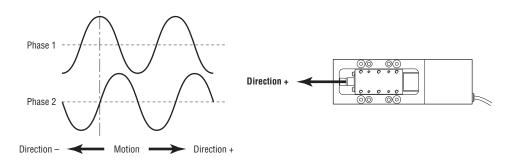


### **Motor**

### **5.1 UE16PP Motor Characteristics**

Motor	Angle by Micro-Step	Current	Resistance	Inductance	Newport
Motor	(°)	(A)	$(\Omega)$	(mH)	Utilization
UE16PP	0.23	0.25	12.5	5.5	Micro-Step

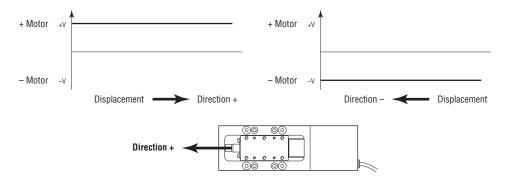
### 5.2 Command Signals for the Stepper Motor



### 5.3 UE1724SR Motor Characteristics

Motor	Ctoro	Nominal	Max. RMS	Max. Peak	Resistance	Inductance
MOTOL	Stage	Voltage (V)	Current (A)	Current (A)	$(\Omega)$	(mH)
UE1724SR	MFA-CC	24	0.15	0.21	54.6	1.19

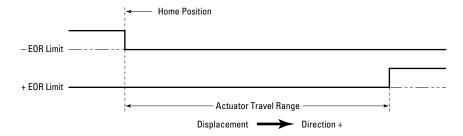
### 5.4 Command Signals for the DC-Motor



In the above drawings, + Motor signal is referred to – Motor signal.

- When the stage moves in + Direction, the + Motor voltage is higher than Motor voltage.
- When the stage moves in Direction, the + Motor voltage is lower than Motor voltage.

### 5.5 Sensor Position



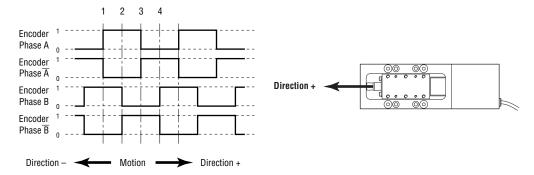
End-of-Run are TTL type: 5 V ±5%, 16 mA max.



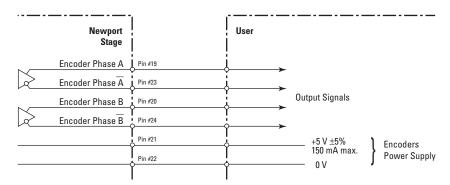
### **CAUTION**

"End-of-Run" are active signals and should not be connected to any other source. Use appropriate TTL type receivers.

### 5.6 Feedback Signal Position for the MFA-CC



The incremental sensor consists of a optical scale and an encoder head. When the sensor shaft turns, the encoder head generates square signals in quadrature, sent to pins #19, #20, #23 and #24 of the 25-pin Sub-D connector.



Encoders are "differential pair" (type RS422) type output signals. Using these signals permits a high immunity to noise. Emission circuits generally used by Newport are 26LS31 or MC3487. Reception circuits to use are 26LS32 or MC3486 respectively.

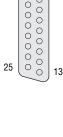
#### **5.7 Pinouts**

The 25-pin Sub-D connections for MFA-PPD and MFA-CC stages are given in the following table:

			UE16PP		UE1724SR		
			MFA-PPD		MFA-CC		
	1	+ Phase 1	1	N.C.			
		2	N.C.	2	N.C.		
		3	– Phase 1	3	N.C.		
		4	N.C.	4	N.C.		
		5	+ Phase 2	5	+ Motor		
		6	N.C.	6	+ Motor		
		7	– Phase 2	7	- Motor		
_	`	8	– Motor	8	- Motor		
000	1	9	N.C.	9	N.C.		
		10	N.C.	10	N.C.		
		11	N.C.	11	N.C.		
		12	N.C.	12	N.C.		
		13	N.C.	13	Mechanical Zero		
000000000000000000000000000000000000000		14	N.C.	14	Shield Ground		
	13	15	N.C.	15	N.C.		
$\sim$	,	16	N.C.	16	0 V logic		
		17	+ End-of-Run	17	+ End-of-Run		
		18	– End-of-Run	18	– End-of-Run		
		19	N.C.	19	Encoder Phase A		
		20	N.C.	20	Encoder Phase B		
		21	+5 V	21	Encoder Power: +5 V		
		22	0 V	22	0 V Encoder		
		23	N.C.	23	Encoder Phase /A		
		24	N.C.	24	Encoder Phase /B		
		25	N.C.	25	N.C.		

The 9-pin Mini-DIN connection for the MFA-PP stage is given in the following table:

	UE16PP	
	MFA-PP	
1	– End-of-Run	
2	Phase 1a	
3	+5 V	
4	Phase 2b	
5	N.C.	
6	Phase 2a	
7	Phase 1b	
8	0 V	
9	+ End-of-Run	



### **Connection to Newport Controllers**

### 6.1 Warnings on Controllers

Controllers are intended for use by qualified personnel who recognize shock hazards and are familiar with safety precautions required to avoid possible injury. Read the controller user's manual carefully before operating the instrument and pay attention to all written warnings and cautions.

#### WARNING

Disconnect the power plug under the following circumstances:

- If the power cord or any attached cables are frayed or damaged in any way.
- If the power plug is damaged in any way.
- If the unit is exposed to rain, excessive moisture, or liquids are spilled on the unit.
- If the unit has been dropped or the case is damaged.
- If you suspect service or repair is required.
- Whenever you clean the electronics unit.

#### **CAUTION**

To protect the unit from damage, be sure to:

- Keep all air vents free of dirt and dust.
- Keep all liquids away from the unit.
- Do not expose the unit to excessive moisture (85% humidity).

• Read this manual before using the unit for the first time.



### WARNING

All attachment plug receptacles in the vicinity of this unit are to be of the grounding type and properly polarized.

Contact your electrician to check your receptacles.

### **WARNING**

This product is equipped with a 3-wire grounding type plug.

Any interruption of the grounding connection can create an electric shock hazard.

If you are unable to insert the plug into your wall plug receptacle, contact your electrician to perform the necessary alterations to ensure that the green (green-yellow) wire is attached to earth ground.

### **WARNING**

This product operates with voltages that can be lethal.

Pushing objects of any kind into cabinet slots or holes, or spilling any liquid on the product, may touch hazardous voltage points or short out parts.

### 6.2 Connection

On each stage is represented a label which indicates its name and its serial number.



### WARNING

Always turn the controller's power OFF before connecting to a stage.

Stages may be connected to the rear panel motor connectors any time prior to power-up with the supplied cable assemblies.

### **NOTE**



MFA are ESP compatible stages. Enhanced System Performance is Newport's exclusive technology that enables Newport ESP motion controllers to recognize the connected Newport ESP stage and upload the stage parameters. This ensures that the user can operate the motion system quickly and safely.



### **Connection to Non-Newport Electronics**



#### **WARNING**

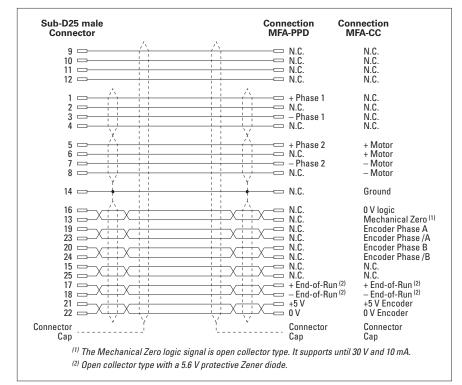
Newport takes no responsibility for improper functioning or damage of a stage when it is used with any non-Newport controllers.

### 7.1 MFA-CC Stages

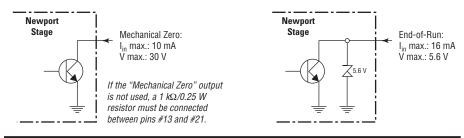
#### WARNING

Newport guarantees the "(f" compliance of the MFA translation stages only if they are used with Newport cables and controllers.

Nevertheless, the figure below indicates the recommended wiring when a MFA-CC stage is used with non-Newport controllers.







"Encoder" and "Index Pulse" are "differential pair" type output signals. Using these signals permits a high immunity to noise. Emission circuits generally used by Newport are 26LS31 or MC3487. Reception circuits to use are 26LS32 or MC3486.

### 7.2 MFA-PP Stages

#### **WARNING**

MFA-PP stages are equipped with a 9-pin mini-DIN non-standard connector and must only be used with our Newport NSC200 controller/driver.

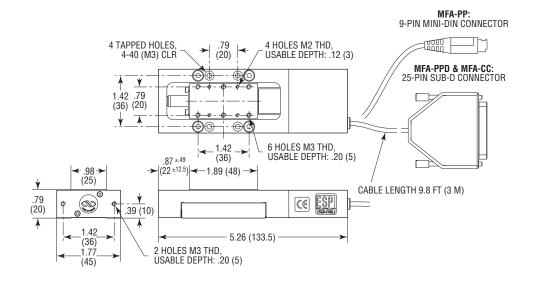


NSC200 Single-Axis Low-Power Motion Controller/Driver.

8.0

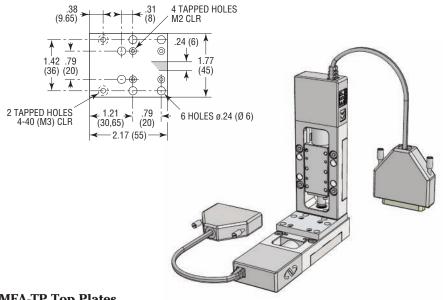
### **Dimensions**

### 8.1 MFA Stages

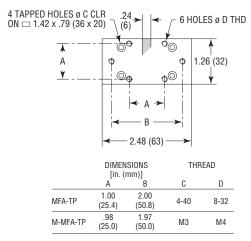


### 8.2 MFA-BK Plate

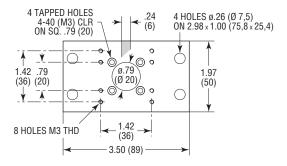
The MFA-BK top plate is used for XZ and XYZ assemblies with MFA stages.



### 8.3 (M-)MFA-TP Top Plates



### 8.4 MFA-BP Base Plate



### **NOTE**

These plates are not included with MFA stages and must be ordered separately.

#### **Maintenance**

#### RECOMMENDATION

It is recommended to contact Newport's After Sales Service to define the appropriate maintenance for your application.

#### 9.1 Maintenance

The MFA stage requires no particular maintenance. Nevertheless, this is a precision mechanical device that must be kept and operated with caution.

#### **PRECAUTIONS**

The MFA stage must be used or stocked in a clean environment, without dust, humidity, solvents or other substances.

#### RECOMMENDATION

It is recommended to return your stage to Newport's After Sales Service after every 2000 hours of use for lubrication and maintenance.

If your MFA stage is mounted on a workstation and cannot be easily removed, please contact Newport's After Sales Service for further instructions.

### 9.2 Repair



#### **CAUTION**

Never attempt to disassemble a component of the stage that has not been covered in this manual.

To disassemble a non specified component can cause a malfunction of the stage.

If you observe a malfunction in your stage, please contact us immediately to arrange for a repair.



### **CAUTION**

Any attempt to disassemble or repair a stage without prior authorization will void your warranty.

#### 9.3 Calibration



### **CAUTION**

It is recommended to return your stage to Newport once a year for recalibration to its original specifications.

# **Service Form**

Name:	Return authorization #:(Please obtain prior to return of item)	
Company:	(Flease obtain prior to return of item)	
Address:	Date:	
Country:	Phone Number:	
P.O. Number:	Fax Number:	
Item(s) Being Returned:		
Model #:	Serial #:	
Description:		
Reasons of return of goods (please list	t any specific problems):	

**Your Local Representative** 

Fax: \_\_



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